

Amendments to the Specification:

Please replace paragraph [0020] with the following amended paragraph:

[0020] FIG. 4 is an exploded perspective view of the apparatus of the present invention, showing in particular, the components of the invention including a first side of the actuator assembly; [[and]]

Please add the following new paragraph after paragraph [0020]:

[0020.1] FIG. 4a is an enlarged view of an adjustment follower of FIG. 4; and

Please replace paragraph [0028] with the following amended paragraph:

[0028] To provide sufficient mechanical advantage for lever operation in the embodiment shown, the moment arm $\underline{MA_1}$ defined by the perpendicular distance between the cable securing assembly 42 and the pivot axis 44 is smaller than the moment arm $\underline{MA_2}$ defined by the perpendicular distance between the actuator tab 46 and the pivot axis 44. With a larger actuator tab moment arm $\underline{MA_2}$, the force required by the user to actuate the lever arm 24 and change the suspension setting[[],] is further reduced.

Please replace paragraph [0029] with the following amended paragraph:

[0029] The actuator control assembly 16 is shown in FIGS. 1-5 as comprising a locking assembly 26 and an adjustment assembly 28. It will be understood that the actuator control assembly 16 is configured to facilitate rider positioning of the lever arm 24 in a first position 21 corresponding to a first suspension setting (in a preferred embodiment, a substantially rigid suspension setting with little travel), as well as facilitating rider positioning of the lever arm 24 in a second position 23 corresponding to a second suspension setting (in a preferred embodiment, a softer setting than the first suspension setting wherein the suspension is permitted a predetermined amount of travel). In the embodiment shown,

downward pivotal motion of the lever arm 24 by the rider locates the lever arm in the first position 21, while upward pivotal motion of the lever arm locates the lever arm in the second position 23. Additionally, in the embodiment shown, the control cable 102 preferably biases the lever arm 24 in the second position 23.

Please replace paragraph [0034] with the following amended paragraph:

[0034] The adjustment follower 70 is shown in FIG. 4 as comprising a pin 78 and a carrier 81. The carrier 81 includes a threadform 79 ~~(not shown)~~ configured to matingly engage the threadform 74 of the adjustment screw 68 (see FIG. 4a). The adjustment follower 70 is configured to translate but not rotate, preferably within a bore 88 of body 12, while the adjustment screw is configured to rotate ~~[[by]]~~ but not translate within the same bore 88, such that as the adjustment screw 68 is rotated, follower 70 translates along the adjustment screw, and in turn, along the bore 88. The adjustment guide surface 64 is configured to contact the pin 78 of the adjustment follower 70 when the actuator assembly 14 is in the second position. The position of the adjustment follower 70 within the bore 88 of the body 12 can be variably adjusted by the rider by rotating the adjustment screw 68 to a desired second position of the lever arm 24, and in turn, a desired second suspension setting.